# Quantum Computing @ MEF Background

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# 1 Quantum States

Models of computation often put at center stage a notion of state and a corresponding notion of state transition [BM17]. In the quantum world, states usually involve superpositions, angles, and lengths; or in other words, they involve aspects related to geometry. This suggests us to familiarise with both the notion of a *vector space* and (the more refined) notion of an *inner product space*. It also suggests us to delve deep into the inner workings of maps between vector spaces and maps between inner product spaces, both intuitively yielding a notion of a quantum state transition (i.e. a quantum operation).

## 1.1 Vector spaces

Let  $\mathbb{C}$  denote the set of complex numbers.

**Definition 1** (Vector Space). A vector space (over the complex numbers) <sup>1</sup> is a set V together with an 'addition' operation  $+ : V + V \to V$ , a 'multiplication' operation  $\cdot : \mathbb{C} \times V \to V$ , a 'zero' element  $0 \in V$ , and an 'inverse' operation  $- : V \to V$  such that the following equations hold for arbitrary  $v, u, w \in V$ ,  $s, r \in \mathbb{C}$ :

$$\begin{array}{ll} v + (u + w) = (v + u) + w & v + u = u + v \\ v + 0 = v & v + (-v) = 0 \\ (sr) \cdot v = s \cdot (r \cdot v) & 1 \cdot v = v \\ s \cdot (v + u) = s \cdot v + s \cdot u & (s + r) \cdot v = s \cdot v + r \cdot u \end{array}$$

To keep notation simple we will often omit the dot of the scalar multiplication, i.e. we will write expressions  $s \cdot v$  simply as sv.

**Example 1.** The complex numbers themselves form a vector space and the set  $\mathbb{C}^2$  of pairs of complex numbers also forms a vector space. This last space underlies the mathematical representation of the state of a qubit. Recall that a qubit is the unit in quantum information. Later on we will see that our notion of state corresponds exactly to the state of a sequence of qubits.

<sup>&</sup>lt;sup>1</sup>In this course we will only consider vector spaces over the complex numbers. Note however that many of the mentioned results hold for a general field.

#### Exercise 1.

- 1. Show that for any finite set n we can build a vector space  $\mathbb{C}^n$  over the complex numbers.
- 2. Show also that the set  $Mat_{\mathbb{C}}(n,m)$  of matrices with n lines and m columns and whose values are complex numbers also forms a vector space (hint: observe that matrices can be given a functional representation).

#### Exercise 2.

Consider the following matrices:

$$Id = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}; X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}; Z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}; H = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}; S = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix};$$
Determine each of the following:

- 1.  $Z \cdot S$
- 2.  $S \cdot S$
- 3.  $H \cdot H$
- 4.  $H \cdot X \cdot H$

**Definition 2** (Linear maps a.k.a. linear operators or simply operators). Consider two vector spaces V and W. A linear map  $f: V \to W$  is a function that satisfies the equations,

$$f(v_1 + v_2) = f(v_1) + f(v_2)$$
  $f(sv) = sf(v)$ 

We call f a *linear isomorphism* or simply isomorphism if it is bijective. When such is the case, we say that V and W are isomorphic to each other (i.e. essentially the same), in symbols  $V \simeq W$ .

#### Exercise 3.

Show that if  $f: V \to W$  and  $g: W \to U$  are linear maps then their composition  $g \cdot f: V \to U$  is also a linear map.

A crucial concept for our notion of state and state transition is that of a tensor. In essence, it allows to mathematically represent the state of a *sequence* of qubits (instead of working with just one qubit).

**Definition 3** (Tensor). Let V and W be two vector spaces. Their tensor, denoted by  $V \otimes W$ , is the vector space consisting of all linear combinations  $\sum_{i \leq n} s_i(v_i \otimes w_i)$  with  $s_i \in \mathbb{C}, v_i \in V$ ,  $w_i \in W$ , that satisfies the equations,

$$v \otimes w + u \otimes w = (v + u) \otimes w \qquad v \otimes w + v \otimes u = v \otimes (w + u)$$
$$s(v \otimes w) = (sv) \otimes w \qquad s(v \otimes w) = v \otimes (sw)$$

Another concept that will be imensely useful in the course is that of a basis.

**Definition 4** (Basis). A basis for a vector space V is a set  $B \subseteq V$  of vectors that respects the following conditions:

- for every  $v \in V$ , we can find  $v_1, \ldots, v_n \in B$  and  $s_1, \ldots, s_n \in \mathbb{C}$  such that  $\sum_{i \le n} s_i v_i = v$
- for every sequence of vectors  $v_1, \ldots, v_n \in B$  and sequence of complex numbers  $s_1, \ldots, s_n \in \mathbb{C}$  if  $\sum_{i \leq n} s_i v_i = 0$  then  $s_i = 0$  for all  $i \leq n$ .

**Example 2.** The set  $\{1\}$  is a basis for  $\mathbb{C}$  and the set  $\{(1,0), (0,1)\}$  is a basis for  $\mathbb{C}^2$ .

Let B be a basis for a vector space V. If B has n elements we say that V is n-dimensional. If B is finite we say that V is *finite-dimensional*.

In this course we are primarily interested in finite-dimensional vector spaces. Intuitively, this is justified by the fact we will only need to work with a finite number of qubits at a time. Thus from now on all vector spaces that we consider are finite-dimensional.

#### Exercise 4.

Let n be a natural number and  $\mathbb{C}^n$  be the vector space of n-tuples of complex numbers. Present a basis for  $\mathbb{C}^n$  and subsequently indicate its dimension.

Matrices provide a very convenient way of representing states and also of representing state transitions. Let us analyse how such a representation works. Let V and W be vector spaces,  $\{b_1, \ldots, b_n\}$  a basis for V and  $\{c_1, \ldots, c_m\}$  a basis for W. Consider then a linear map  $f: V \to W$ and observe that for every  $i \leq n$  we have  $f(b_i) = \sum_{j \leq m} s_{ij}c_j$  for some  $s_{i1}, \ldots, s_{im} \in \mathbb{C}$ . We obtain a matrix representation  $M \in Mat_{\mathbb{C}}(m, n)$  of f by setting  $M_{ji} = s_{ij}$ . Conversely, consider a matrix  $M \in Mat_{\mathbb{C}}(m, n)$ . It induces a linear map  $f: V \to W$  by setting  $f(b_i) = \sum_{j \leq m} M_{ji}c_j$ . Exercise 5.

- 1. What is the matrix representation of the linear map  $f : \mathbb{C}^2 \to \mathbb{C}^2$  defined by f(1,0) = (0,1)and f(0,1) = (1,0)?
- 2. What is the matrix representation of the linear map  $f : \mathbb{C}^2 \to \mathbb{C}^2$  defined by  $f(1,0) = \frac{1}{\sqrt{2}}(1,0) + \frac{1}{\sqrt{2}}(0,1)$  and  $f(0,1) = \frac{1}{\sqrt{2}}(1,0) \frac{1}{\sqrt{2}}(0,1)$ ?

Before moving forward in the course, we need to fix extra notation. Specifically, we will use  $M: n \to m$  to denote a matrix M with n lines, m columns, and whose values are complex numbers. Also for two matrices  $M: n \to m$  and  $N: m \to o$ , we will use  $MN: n \to o$  to denote the matrix multiplication of M with N. Finally, given a linear map  $f: V \to W$  such that V and W have dimension n and m, respectively, we will use  $M_f: m \to n$  to denote the corresponding matrix.

#### Exercise 6.

Let  $B \subseteq V$ ,  $C \subseteq W$  be bases for vector spaces V and W, respectively. Show that the set  $\{b \otimes c \mid b \in B, c \in C\}$  is a basis for  $V \otimes W$ .

Consider matrices  $M : n \to m$  and  $N : o \to p$ . Their tensor  $M \otimes N : n \cdot o \to m \cdot p$  (also called Kronecker product) is defined by,

$$M \otimes N = \begin{bmatrix} M_{1,1} \cdot N, & \dots, & M_{1,m} \cdot N \\ \vdots & \vdots & \vdots \\ M_{n,1} \cdot N, & \dots, & M_{n,m} \cdot N \end{bmatrix}$$

Exercise 7.

Consider the matrices in exercise 2. Determine each of the following:

- 1.  $H \otimes Id$
- 2.  $Id \otimes X$
- 3.  $Id \otimes (H \cdot Z \cdot H)$

**Definition 5** (Tranpose). Let A be a matrix. A[j,k] represents the *j*-th row , *k*-th column element of A. The transpose of A is

$$A^{T}[j,k] = A[k,j] \tag{1}$$

Definition 6 (Conjugate).

$$\overline{A}[j,k] = \overline{A[j,k]} \tag{2}$$

Definition 7 (Adjoint).

$$A^{\dagger} = (\overline{A}^T) = (\overline{A^T}) \tag{3}$$

or

$$A^{\dagger}[j,k] = \overline{A[k,j]} \tag{4}$$

#### **1.2** Inner product spaces

Recall that for some complex number c the expression  $c^*$  denotes the *complex conjugate* of c.

**Definition 8** (Inner product space). An inner product space is a vector space V equipped with a function  $\langle \cdot, \cdot \rangle : V \times V \to \mathbb{C}$  (the inner product) that satisfies the conditions,

$$\left\langle v, \sum_{i \le n} s_i v_i \right\rangle = \sum_{i \le n} s_i \cdot \langle v, v_i \rangle \qquad \qquad \langle v, w \rangle = \langle w, v \rangle^*$$
$$\langle v, v \rangle \ge 0 \qquad \qquad \langle v, v \rangle = 0 \text{ entails } v = 0$$

for all  $v, v_i, w \in V$  and  $s_i \in \mathbb{C}$ .<sup>2</sup>

Recall that a norm over a vector space V provides a notion of length to the vector space and is formally defined as a function  $\|\cdot\|: V \to [0, \infty)$  such that the following conditions are satisfied,

$$||v|| = 0 \text{ iff } v = 0 \qquad ||s \cdot v|| = |s| \cdot ||v|| \qquad ||v + w|| \le ||v|| + ||w||$$

for all  $v, w \in V$ ,  $s \in \mathbb{C}$ . Moreover, every inner product space V induces a norm  $\|\cdot\| : V \to [0, \infty)$  defined by  $\|v\| = \sqrt{\langle v, v \rangle}$ .

As we will see, the mathematical representation of the state of *n*-qubits is a vector  $v \in \mathbb{C}^{2^n}$ with norm ||v|| = 1.

<sup>&</sup>lt;sup>2</sup>Since we assume that all vector spaces at hand are finite-dimensional we can see inner product spaces as Hilbert spaces.

Exercise 8 (Vector normalisation).

Let  $v \in V$  be a vector. Show that,

$$\left\|\frac{v}{\|v\|}\right\| = 1$$

**Definition 9** (Orthonormal basis). Two vectors  $v, w \in V$  are said to be orthogonal to each other if  $\langle v, w \rangle = 0$ . A basis *B* for an inner product space *V* is called orthonormal if all elements of *B* have norm 1 and all elements  $v \neq w \in B$  are orthogonal to each other.

#### Exercise 9.

Show that the basis  $\{(1,0), (0,1)\}$  for  $\mathbb{C}^2$  is orthonormal.

**Definition 10** (Tensor). Let V and W be two inner spaces. Their tensor, denoted by  $V \otimes W$ , is the tensor of V and W as vector spaces equipped with the function,

$$\left\langle \sum_{i \le n} s_i(v_i \otimes w_i), \sum_{j \le m} r_j(v_j \otimes w_j) \right\rangle = \sum_{i \le n, j \le m} s_i^* r_j \cdot \langle v_i, v_j \rangle \cdot \langle w_i, w_j \rangle$$

When working with linear maps  $f: V \to W$  between inner product spaces V and W we are often interested in those maps that are isometric.

**Definition 11** (Isometry). Consider inner product spaces V and W and a linear map  $f: V \to W$  between them. We call f an isometry if the equation,

$$\langle v_1, v_2 \rangle = \langle f(v_1), f(v_2) \rangle$$

holds for all  $v_1, v_2 \in V$ . Equivalently, f is an isometry iff ||v|| = ||f(v)|| for all  $v \in V$ .

A key property of isometries is they always send unit vectors to unit vectors (because isometries preserve norms). In the particular case of  $V = W = \mathbb{C}^{2^n}$ , this means that quantum states are always mapped to quantum states (and not to something else).

Additionally, quantum physics postulates that quantum operations on an isolated system must be *reversible*. In other words, maps  $f: V \to W$  representing pure quantum operations must have an *inverse*  $f^{-1}: W \to V$  which satisfies  $f^{-1} \cdot f = f \cdot f^{-1} = \text{id}$ . Together with the notion of an isometry, this condition gives rise to the notion of a unitary map.

**Definition 12** (Unitary maps). Let V and W be inner product spaces. A linear map  $f: V \to W$  is called unitary if f is an isometry and surjective<sup>3</sup>.

**Postulate 1** (Quantum state and state transition). The state of an *isolated* quantum computer is given by a unit vector in the space  $\mathbb{C}^{2^n}$  for some finite number n – the number n corresponds to the number of available qubits. State transitions arise via unitary maps, more concretely the state of an isolated quantum computer changes by an application of a unitary map. <sup>4</sup>

The notion of a unitary map can also be formulated via matrices, and often this alternative formulation is easier to work with: let us consider a linear map  $f: V \to V$  and its matrix representation  $M_f: n \to n$ . Then f is unitary iff  $M_f^{\dagger} M_f = M_f M_f^{\dagger} = I$ .

<sup>&</sup>lt;sup>3</sup>Both conditions entail that f has an inverse  $f^{-1}$ .

<sup>&</sup>lt;sup>4</sup>See a more general version of this postulate in Section 2.2 of [NC02]

## Exercise 10.

Show that the following two maps are unitary:

- $f: \mathbb{C}^2 \to \mathbb{C}^2$  defined by f(1,0) = (0,1) and f(0,1) = (1,0).
- $g: \mathbb{C}^2 \to \mathbb{C}^2$  defined by  $g(1,0) = \frac{1}{\sqrt{2}}(1,0) + \frac{1}{\sqrt{2}}(0,1)$  and  $g(0,1) = \frac{1}{\sqrt{2}}(1,0) \frac{1}{\sqrt{2}}(0,1)$ .

Consider a linear map  $f: V \to W$  between inner product spaces V and W. There exists a unique linear map  $f^{\dagger}: W \to V$  such that for all  $v \in V$  and  $w \in W$  the equation,

$$\langle f(v), w \rangle = \langle v, f^{\dagger}(w) \rangle$$

holds. This map is precisely the functional representation of  $M_f^{\dagger}$ .

# References

- [BM17] Roberto Bruni and Ugo Montanari. Models of computation. Springer, 2017.
- [NC02] Michael A Nielsen and Isaac Chuang. Quantum computation and quantum information, 2002.